

Control Flow Graphs



Optimizations

- We wish to apply various program transformations to improve its performance without altering its meaning
- Transformations apply at either high or low IR levels
- Optimizations must be safe
 - That is, the optimized program must give the same results as the un-optimized program for every possible execution



Program meaning is implicit

- The information we require is not necessarily written plainly in the source code
- Consider:
 - x = y + 1 y = 2 * z
 - x = y + z z = 1
 - z = x
- Are all these statements necessary?



Program meaning is implicit

• Some of the statements are dead code

 $x = y + 1 \leftarrow$ This assignment of x...

- y = 2 * z ← ...is not used in any intermediate statement...
- $x = y + z \leftarrow \dots$ until x is assigned again
- $z = 1 \leftarrow$ This assignment of z...
- $z = x \leftarrow ...$ is immediately overwritten
- Noticing this, we can tell that
 - y = 2 * z x = y + z z = x

is an equivalent program

- Control flow is linear here, so dead state is obvious
- It gets harder to tell when control flow gets complicated



Conditions complicate the matter

• Adding some control flow,

x = y + 1 \leftarrow is this statement still dead?y = 2 * zif (c) { x = y + z }z = 1 \leftarrow is this statement still dead?z = x

• The first assignment of x may or may not be used:

x = y + 1 y = 2 * zif (c) { x = y + z } z = 1 z = xx = x

This assignment is relevant when c is false



Loops complicate the matter

• If we insert a loop...

```
while (d) {

x = y + 1 \quad \leftarrow is this statement still dead?

y = 2 * z

if (c) { x = y + z }

z = 1 \quad \leftarrow is this statement still dead?

}

z = x
```

...neither statement can be omitted





Low-level code complicates the matter

 Control flow is more obvious from source code syntax than from its translation into jumps and labels:





What we need

- Methods to compute information that are
 - implicit in the program
 - static (so that it can be found at compile time)
 - valid for every possible dynamic situation (at run time)
- A data structure that can represent every possible control flow
 - Different branches taken (conditionals)
 - Branches taken different numbers of times (loops)
- Problem is similar to that of NFA:

"What are all the possible paths I can take from here?"



Control Flow Graphs (CFGs)

- Program control flow can be captured in a directed graph, where statements make nodes and their sequencing follows the arcs
- Movement of data can be inferred by traversing a structure like this
 - By far the most common approach in present compilers
 (It is also possible to graph data movement and infer control, but let's stick to the control flow view)
- Multiple paths emerge since nodes can have multiple incoming/outgoing arcs



Linear sequences

These are a bit boring:
 a = 1
 b = 2
 c = a + b



• Therefore, we contract them to basic blocks

(but remember that there are separate statements inside...)

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Branches end basic blocks













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When c is false





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Infeasible executions

• Some paths may not correspond to any run





Infeasible executions

 Unless either branch modifies c, this path won't occur, even though the CFG contains it:





Interpretation of arcs

- Without pruning infeasible paths (which may require run-time information), the analysis will remain conservative/safe as long as every actual path is also represented
- Outgoing arcs mean that their destination may be a successor to a basic block
- Incoming arcs mean that any of the source blocks may be a predecessor to a basic block



Recursive CFG construction

- At high level, CFGs can be built by a syntax directed scheme, like our TAC translation patterns:
- CFG (S1; S2; S3; ...; Sn) =





Recursive CFG construction: if-else

• CFG (if (E) S1 else S2) =





Recursive CFG construction: if

• CFG (if (E) S) =





Recursive CFG construction: while

• CFG (while (E) S) =

















Efficiency

 Empty blocks and sequences can be pruned after or during construction





Efficiency

- These graphs grow large
 - It's good to have as few basic blocks as possible
 - They should be as large as possible
- Merge linear subgraphs if
 - B2 is a successor of B1
 - B1 has one outgoing edge
 - B2 has one incoming edge $B1 \rightarrow B2$ should be a block
- Remove empty blocks



At low-level IR

- Split the operation sequence at labels and jumps
 - Labels can have incoming control flow
 - Jumps have outgoing control flow





At low-level IR

- Conditional jump = 2 successors
- Unconditional jump = 1 successor





The outcome is the same

• Both procedures give us equivalent program logic:



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